

# Specifying Control

Based on Chapter 9  
Bennett, McRobb and Farmer  
*Object Oriented Systems Analysis  
and Design Using UML*  
4<sup>th</sup> Edition, McGraw Hill, 2010

# In This Lecture You Will Learn:

- how to identify requirements for control in an application;
- how to model object life cycles using state machines;
- how to develop state machine diagrams from interaction diagrams;
- how to model concurrent behaviour in an object;
- how to ensure consistency with other UML models.

# State

- The current state of an object is determined by the current value of the object's attributes and the links that it has with other objects.
- For example the class `StaffMember` has an attribute `startDate` which determines whether a `StaffMember` object is in the probationary state.

# State

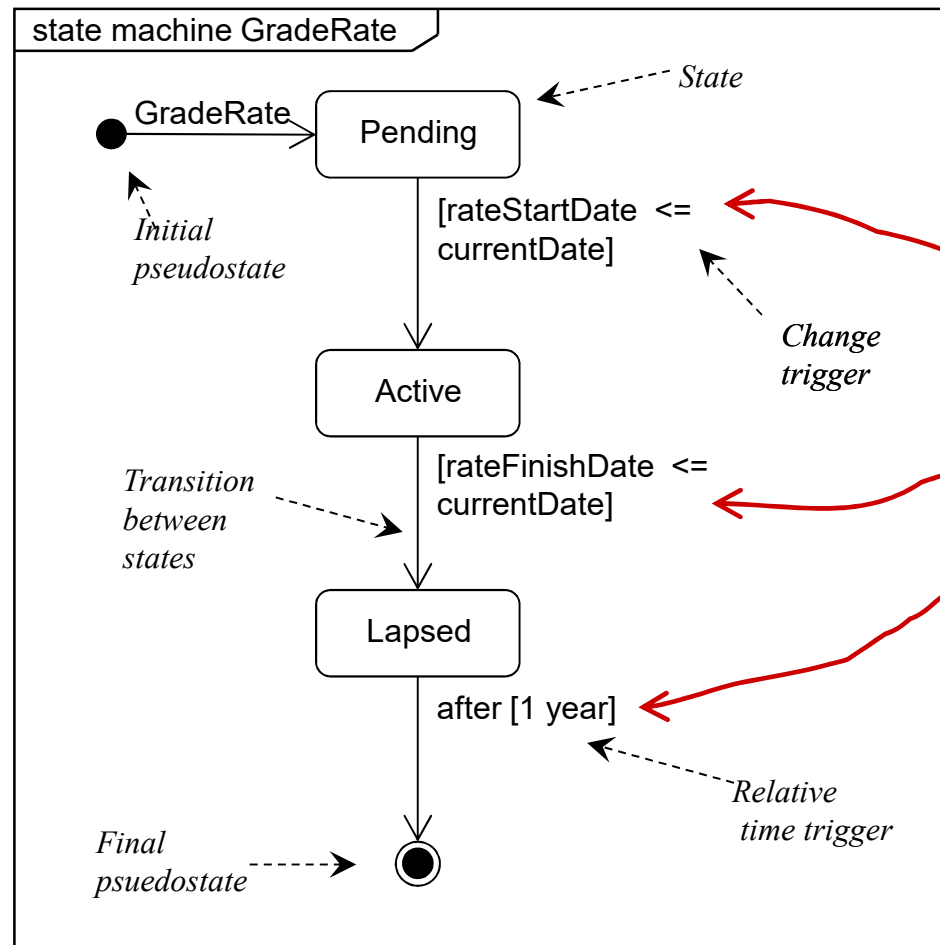
- A state describes a particular condition that a modelled element (e.g. object) may occupy for a period of time while it awaits some event or *trigger*.
- The possible states that an object can occupy are limited by its class.
- Objects of some classes have only one possible state.
- Conceptually, an object remains in a state for an interval of time.

# state machine

- The current state of a `GradeRate` object can be determined by the two attributes `rateStartDate` and `rateFinishDate`.
- An enumerated state variable may be used to hold the object state, possible values would be Pending, Active or Lapsed.

# state machine

state machine for the class GradeRate.

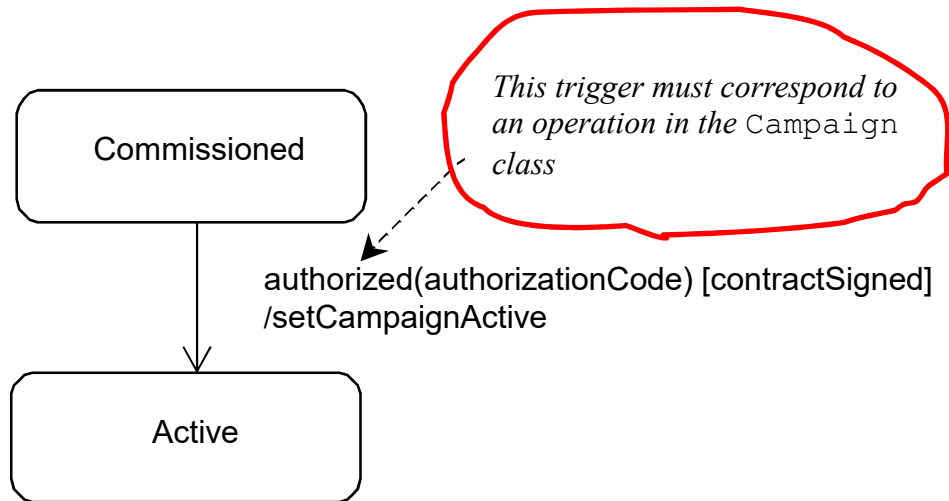


Movement from one state to another is dependent upon events that occur with the passage of time.

# Types of Event

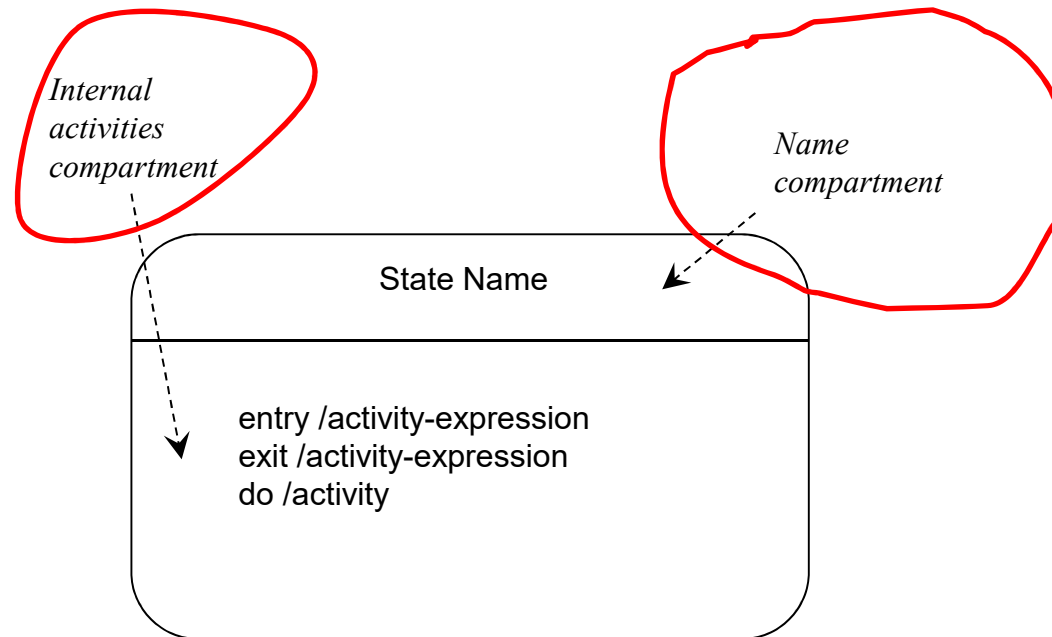
- A *change trigger* occurs when a condition becomes true.
- A *call trigger* occurs when an object receives a call for one of its operations either from another object or from itself.
- A *signal trigger* occurs when an object receives a signal (an asynchronous communication).
- An *relative-time trigger* is caused by the passage of a designated period of time after a specified event (frequently the entry to the current state).

# Events



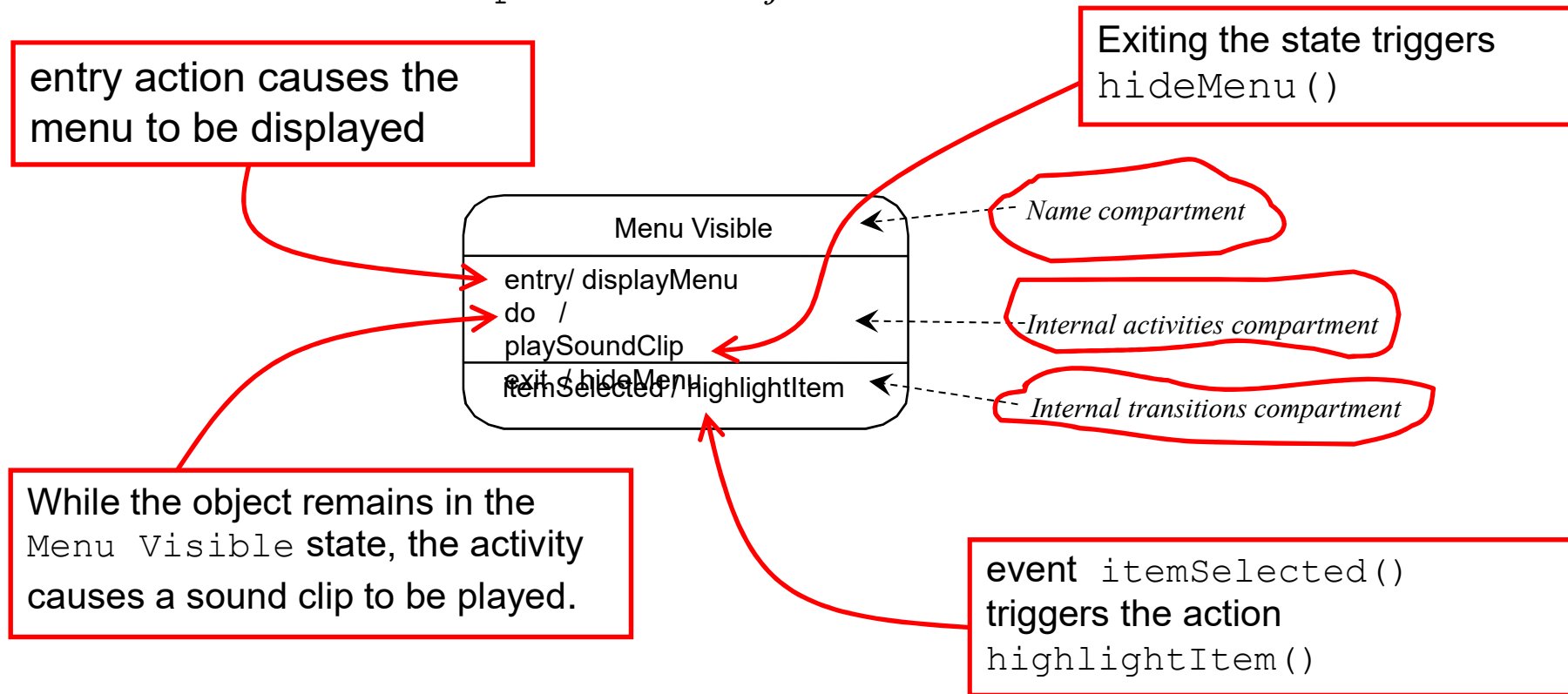


# Internal Activities



# 'Menu Visible' State

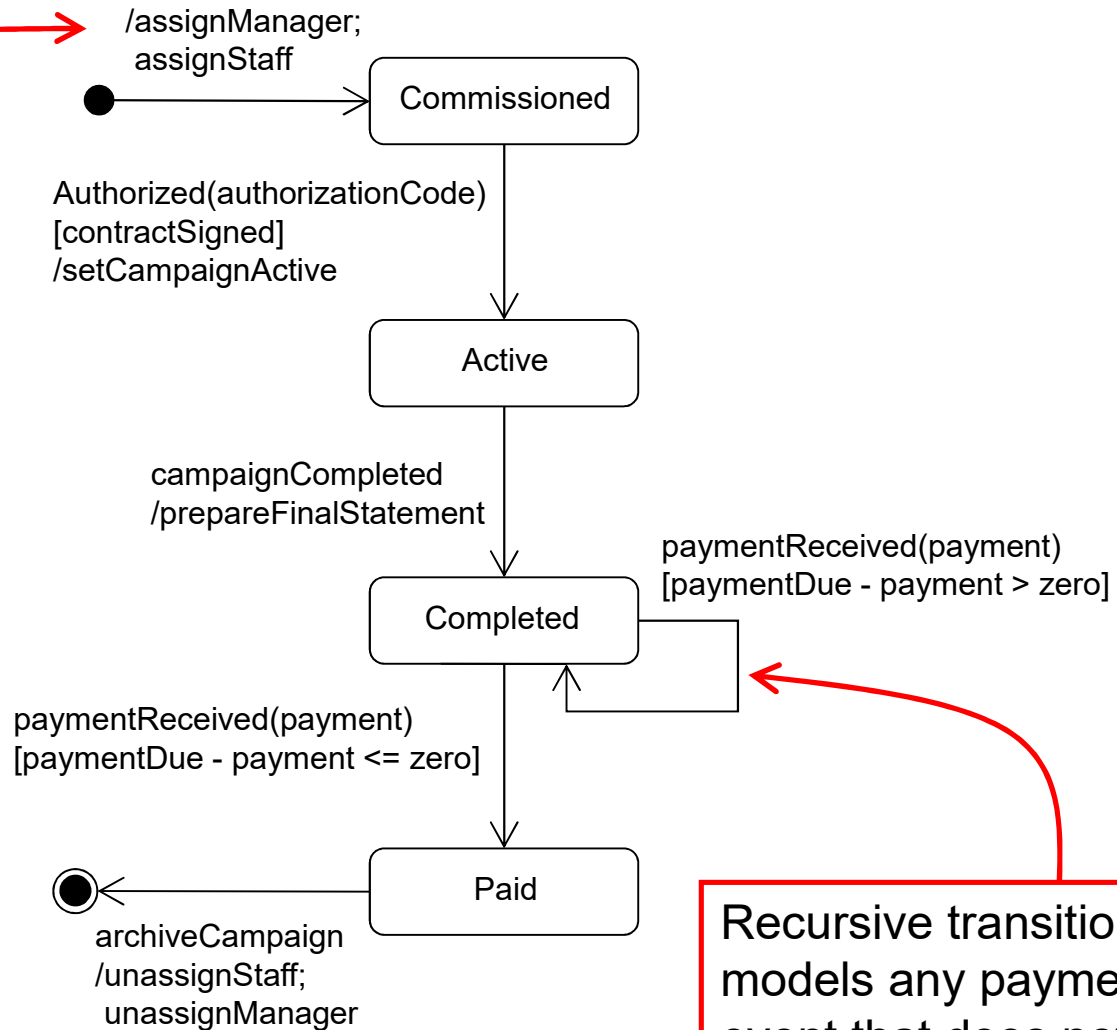
Menu Visible *state for a*  
DropDownMenu *object.*



Action-expression  
assigning manager and  
staff on object creation

state machine  
for the class  
**Campaign.**

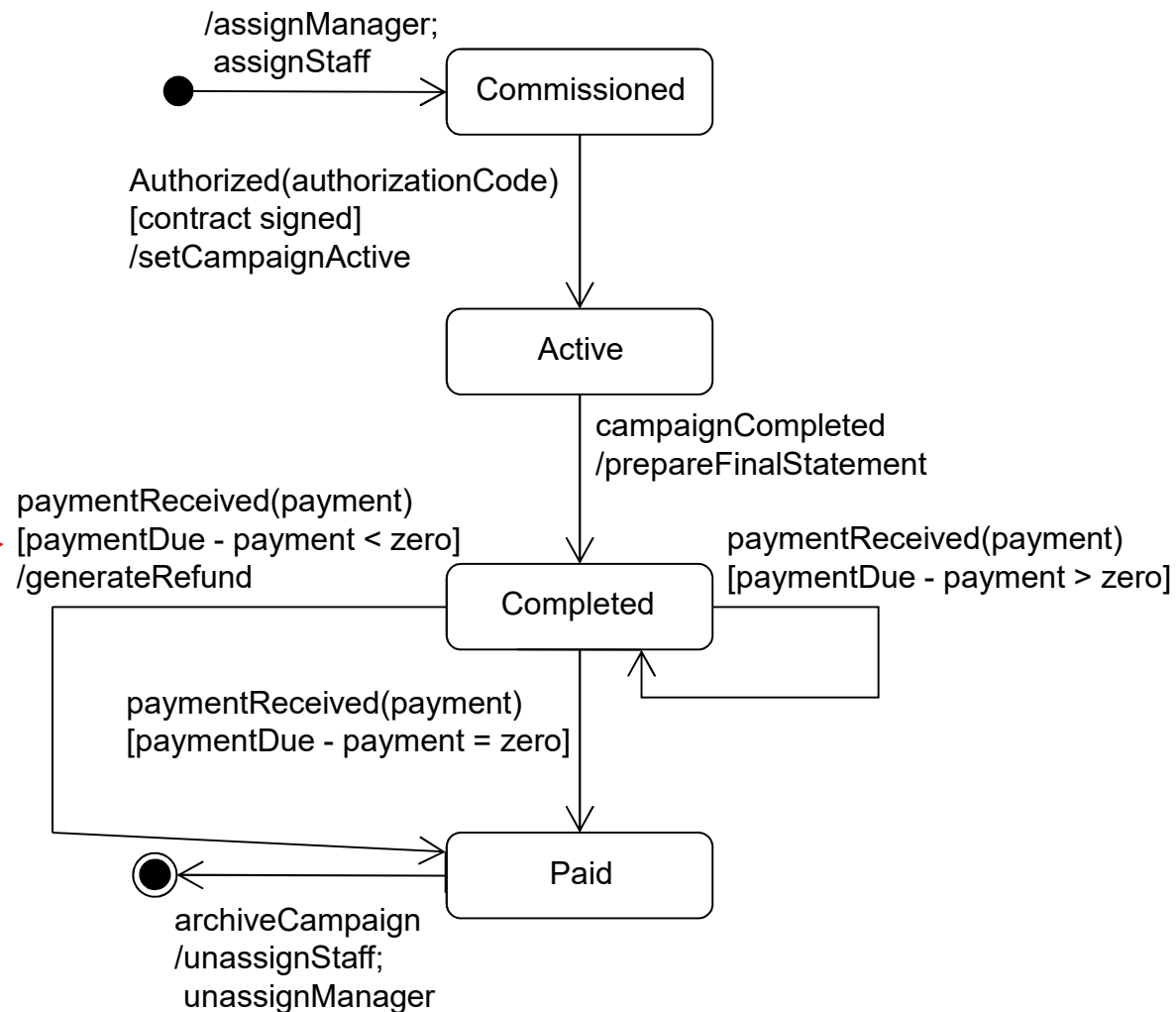
Guard condition ensuring  
complete payment  
before entering `Paid`



Recursive transition  
models any payment  
event that does not  
reduce the amount due  
to zero or beyond.

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## A revised state machine for the class Campaign

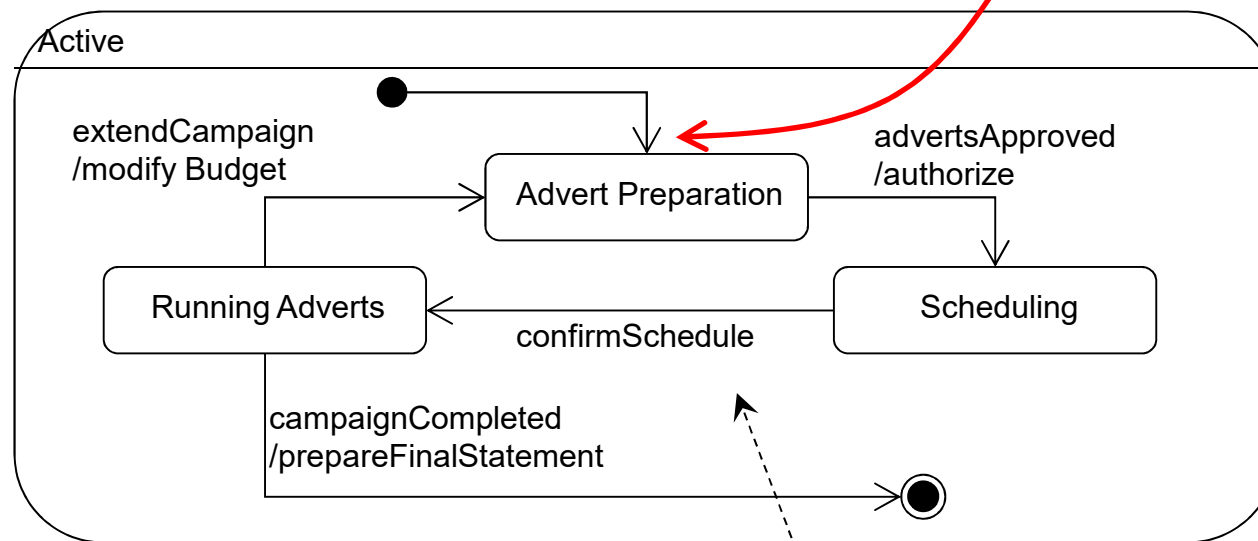


If the user requirements were to change, so that an overpayment is now to result in the automatic generation of a refund, a new transition is added.

# Nested Substates

*The Active state of Campaign showing nested substates.*

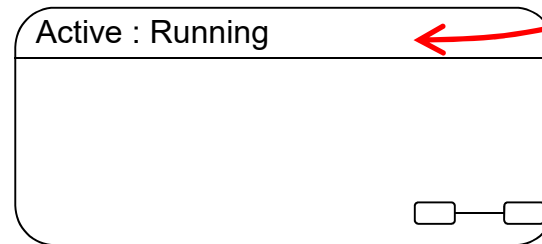
The transition from the initial pseudostate symbol should not be labelled with an event but may be labelled with an action, though it is not required in this example



*Decomposition compartment*

# Nested States

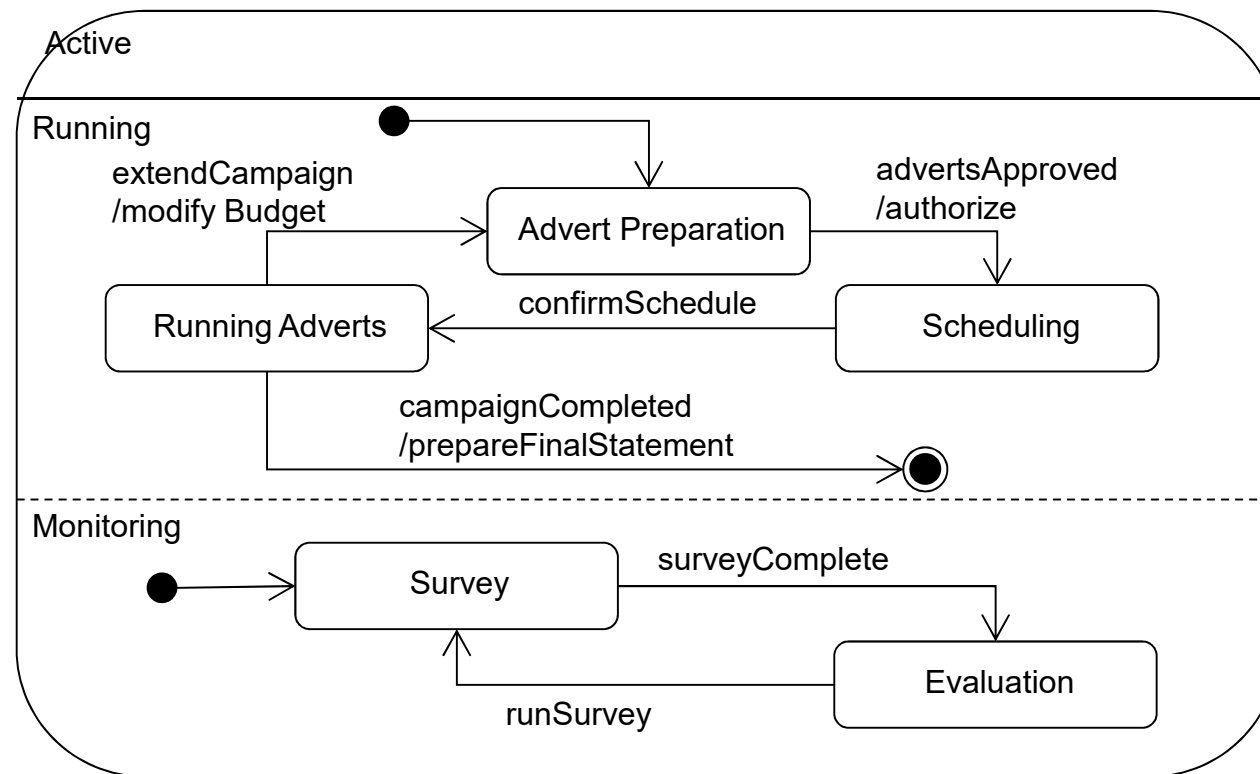
*The Active state of Campaign with the detail hidden.*



The submachine `Running` is referenced using the include statement.

Hidden decomposition indicator icon

# The Active state with concurrent substates.



# Concurrent States

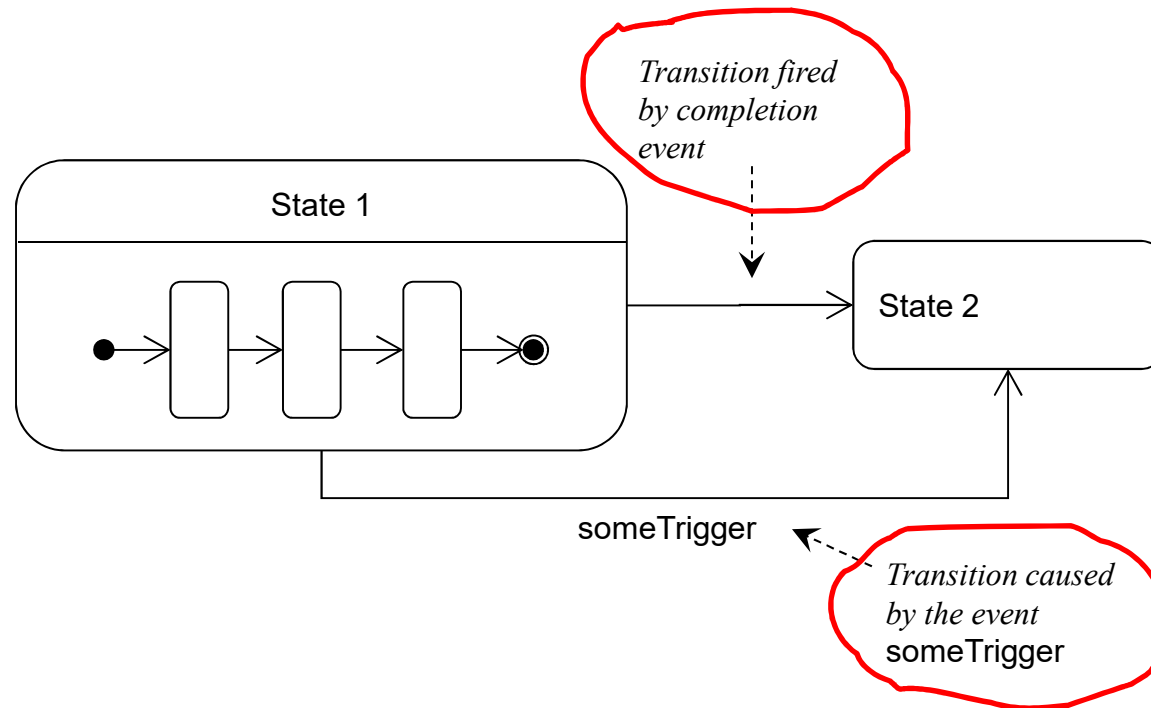
- A transition to a complex state is equivalent to a simultaneous transition to the initial states of each concurrent state machine.
- An initial state must be specified in both nested state machines in order to avoid ambiguity about which substate should first be entered in each concurrent region.
- A transition to the `Active` state means that the `Campaign` object simultaneously enters the `Advert Preparation` and `Survey` states.



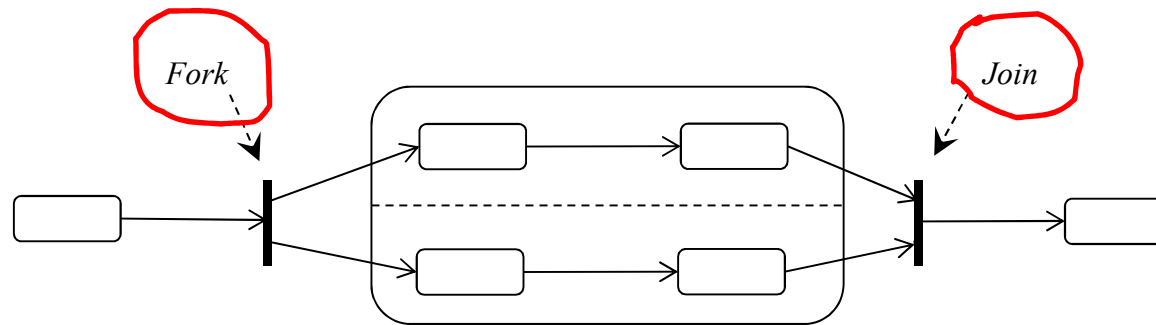
# Concurrent States

- Once the composite state is entered a transition may occur within either concurrent region without having any effect on the state in the other concurrent region.
- A transition out of the `Active` state applies to all its substates (no matter how deeply nested).

# Completion Event

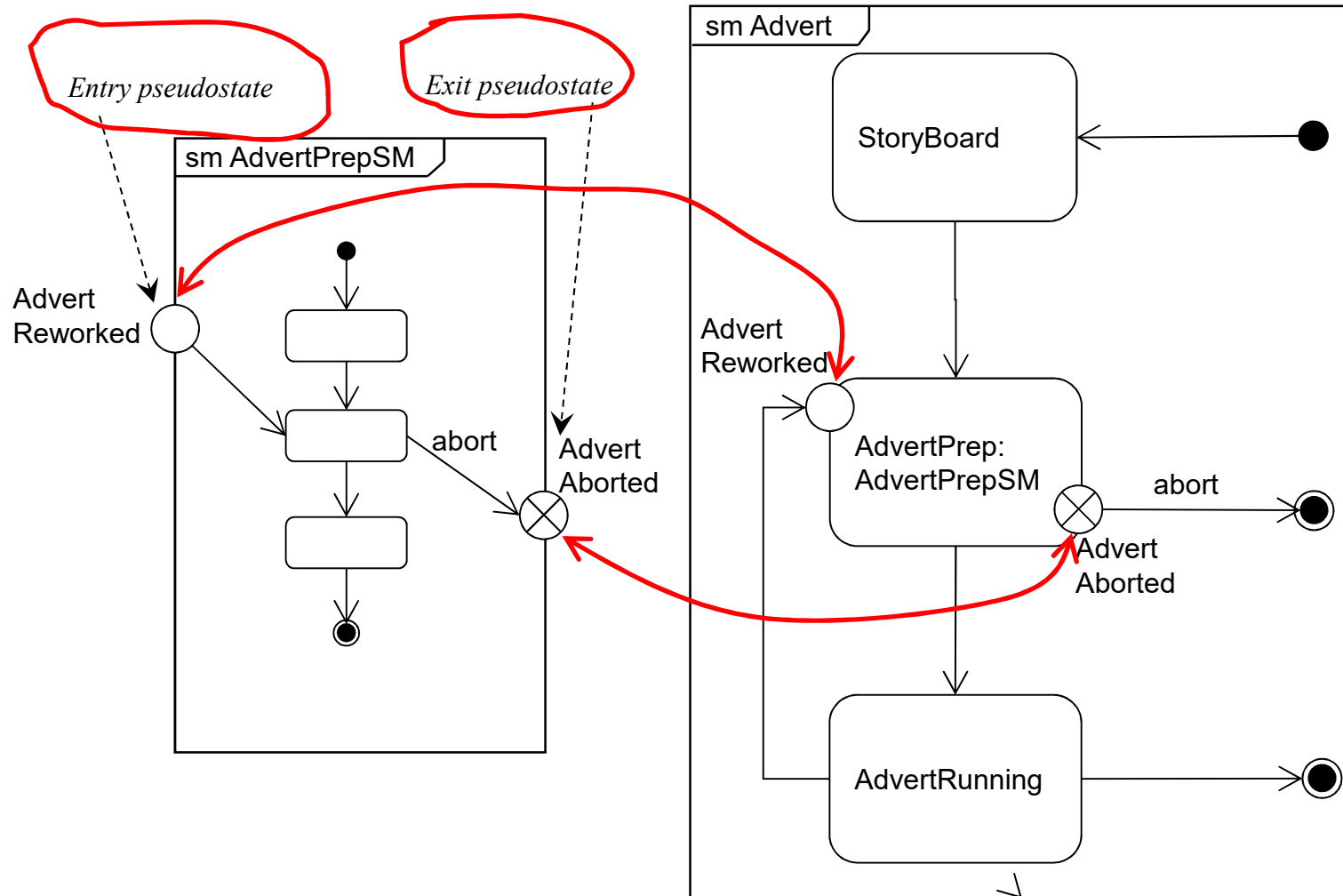


# Synchronized Concurrent Threads.

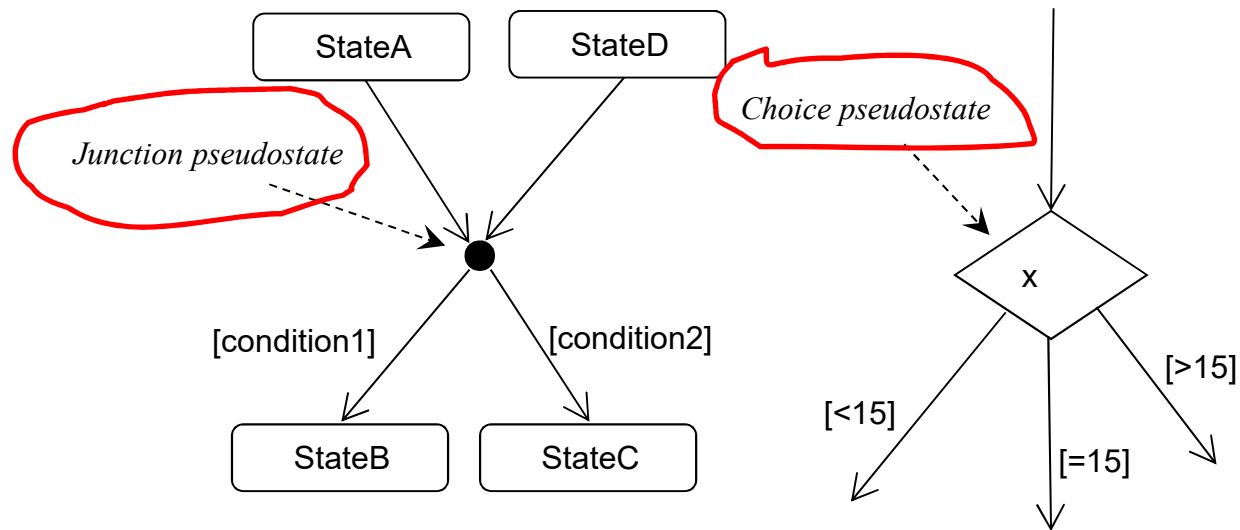


- Explicitly showing how an event triggering a transition to a state with nested concurrent states causes specific concurrent substates to be entered.
- Shows that the composite state is not exited until both concurrent nested state machines are exited.

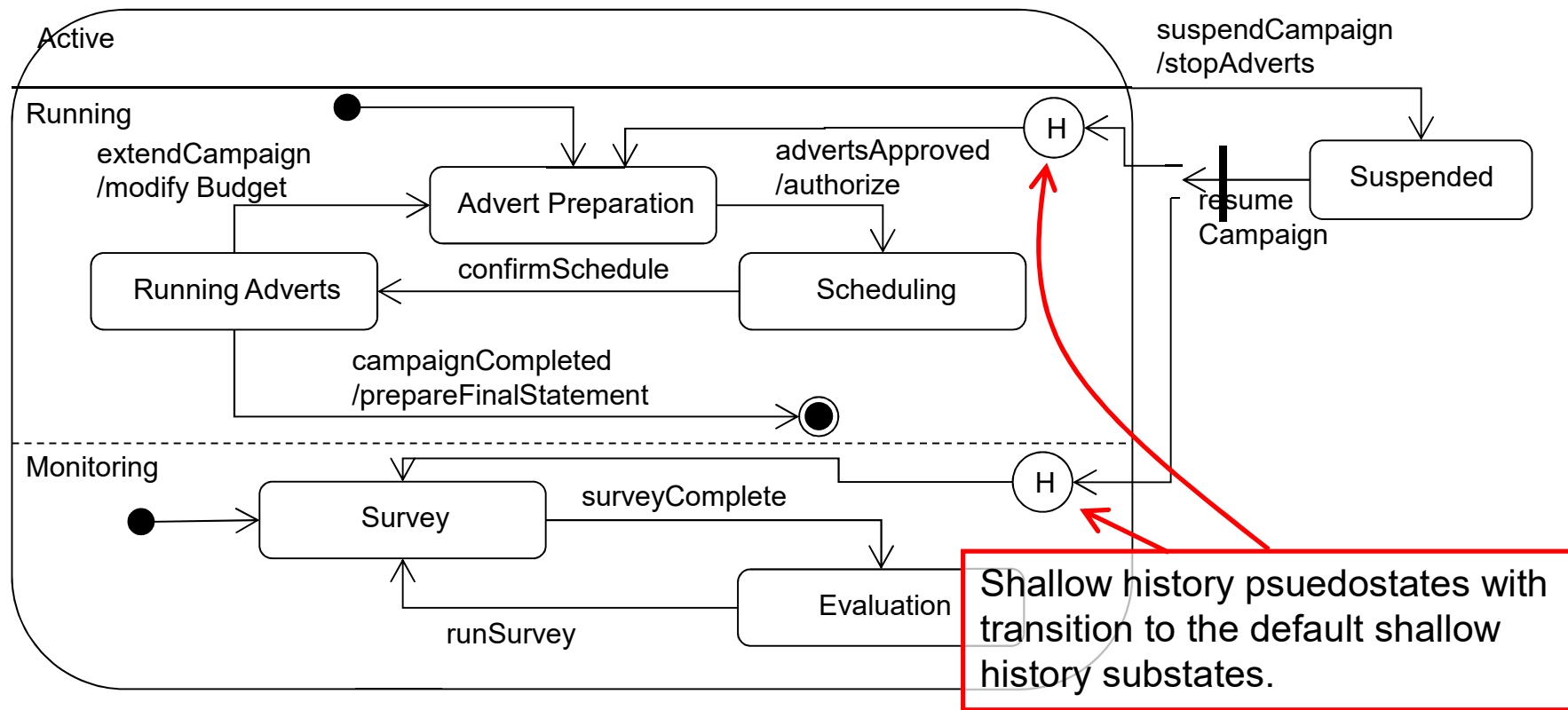
# Entry & Exit Pseudostates



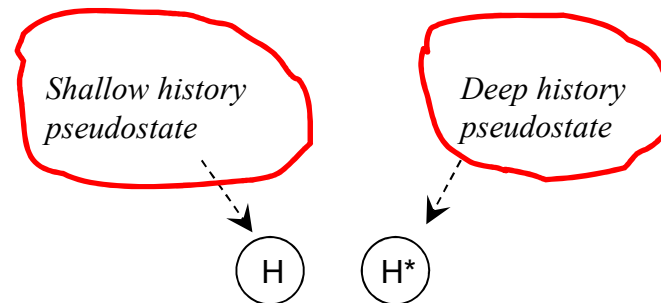
# Junction & Choice Pseudostates



# History Pseudostates



# History Pseudostates



# Preparing state machines

- Two approaches may be used:
  - Behavioural approach
  - Life cycle approach

Allen and Frost (1998)



# Behavioural Approach

1. Examine all interaction diagrams that involve each class that has heavy messaging.
2. Identify the incoming messages on each interaction diagram that may correspond to events. Also identify the possible resulting states.
3. Document these events and states on a state machine.
4. Elaborate the state machine as necessary to cater for additional interactions as these become evident, and add any exceptions.

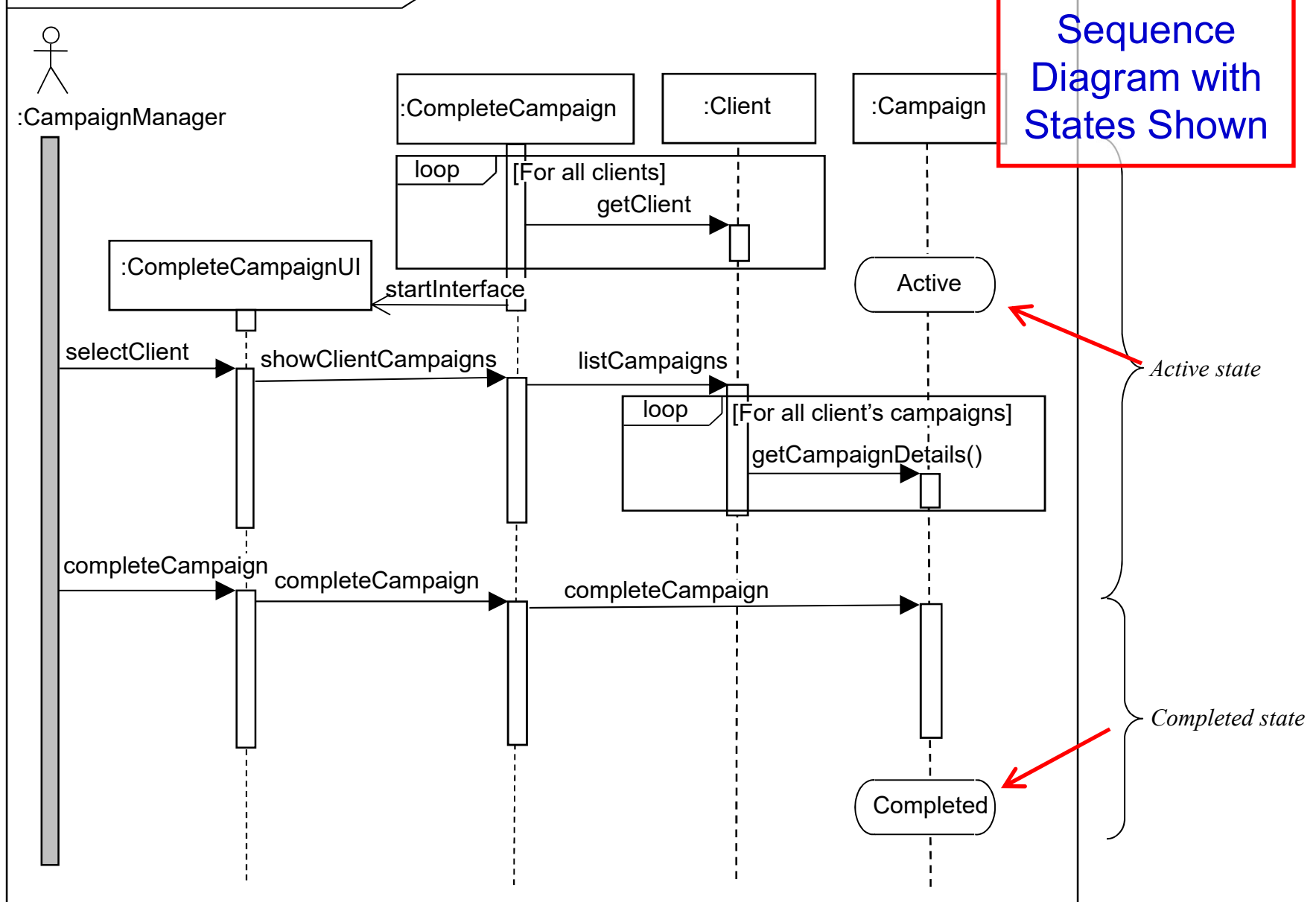
# Behavioural Approach

5. Develop any nested state machines (unless this has already been done in an earlier step).
6. Review the state machine to ensure consistency with use cases. In particular, check that any constraints that are implied by the state machine are appropriate.

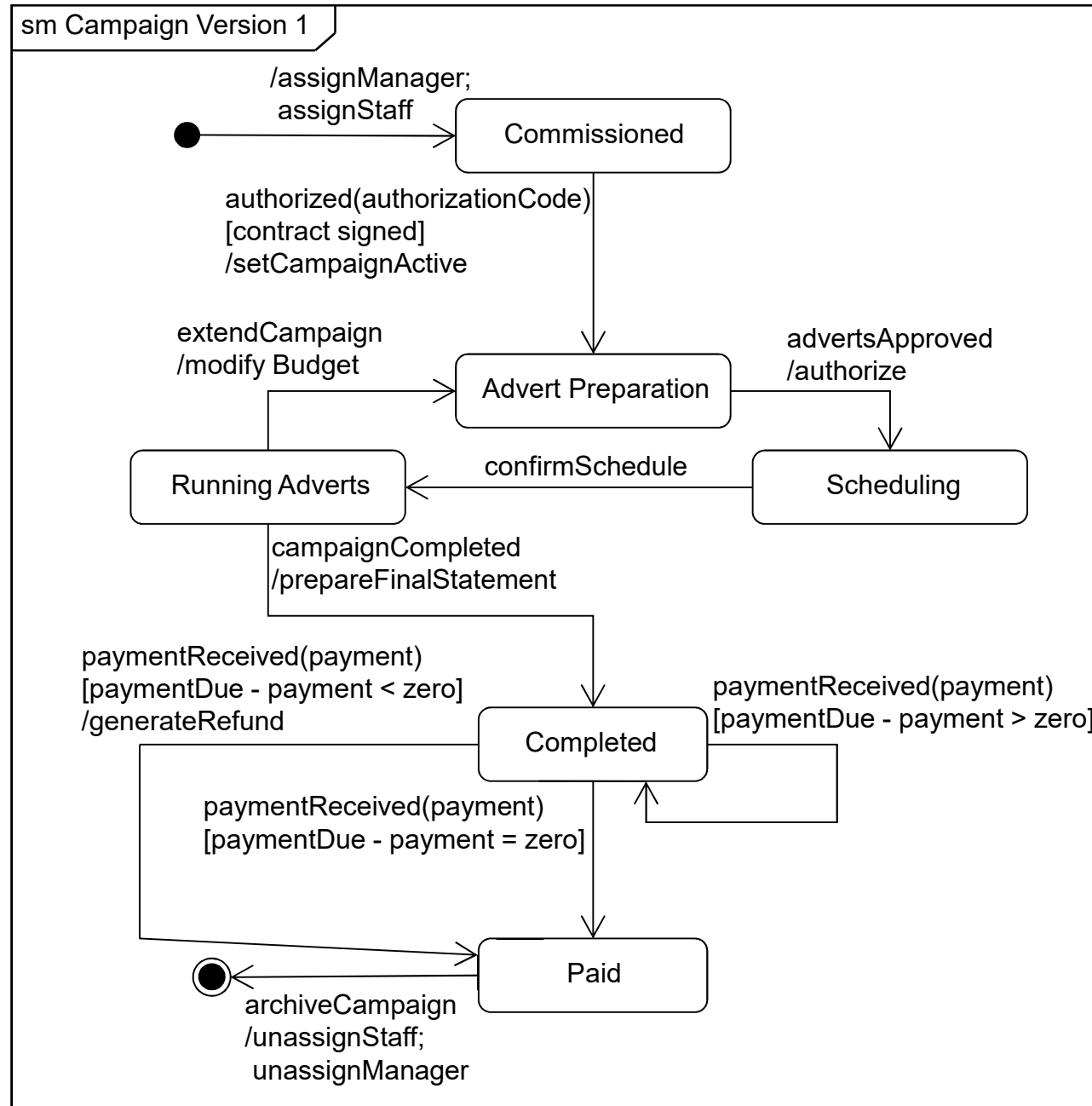
# Behavioural Approach

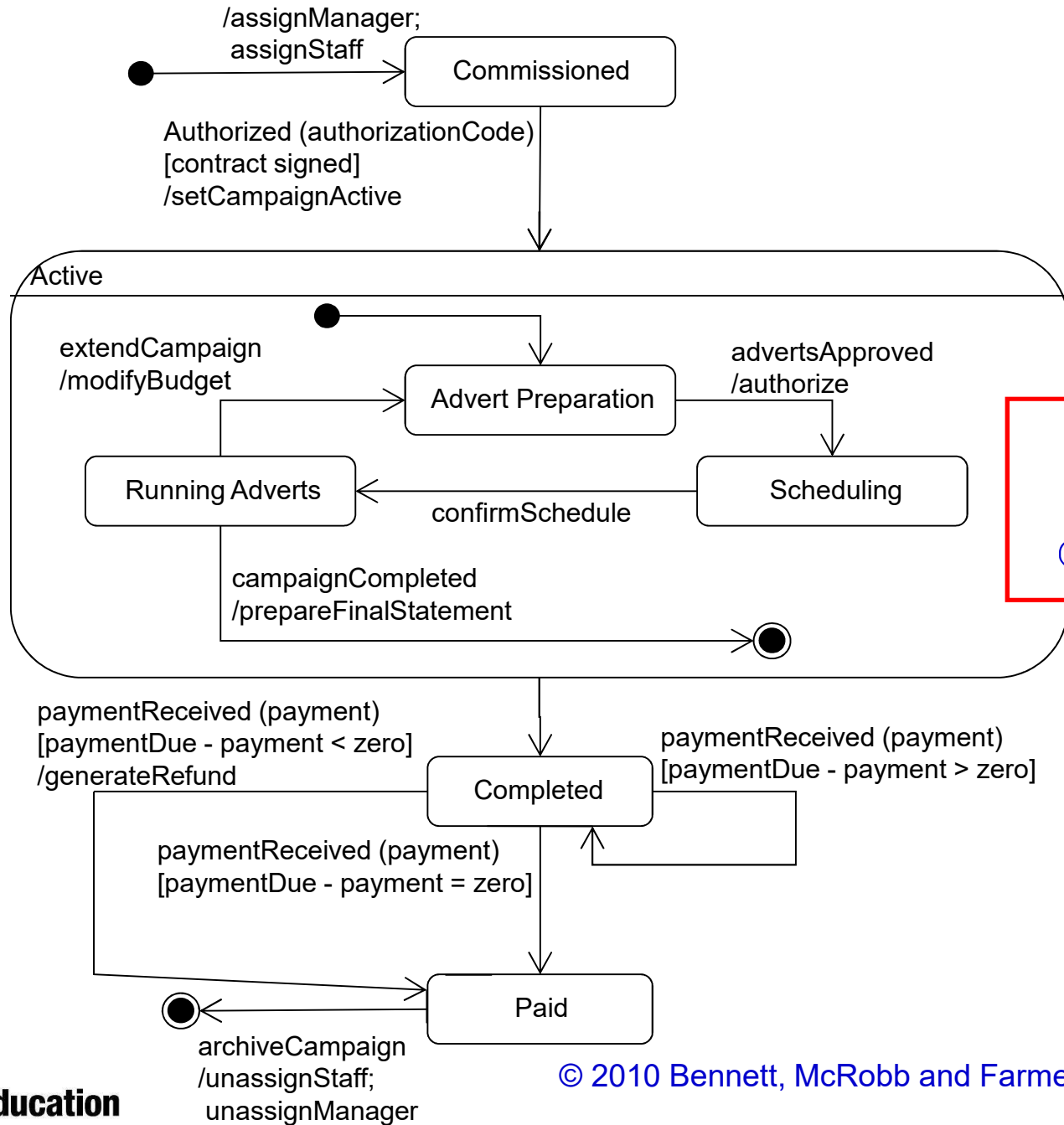
7. Iterate steps 4, 5 and 6 until the state machine captures the necessary level of detail.
8. Check the consistency of the state machine with the class diagram, with interaction diagrams and with any other state machines and models.

sd Record completion of a campaign

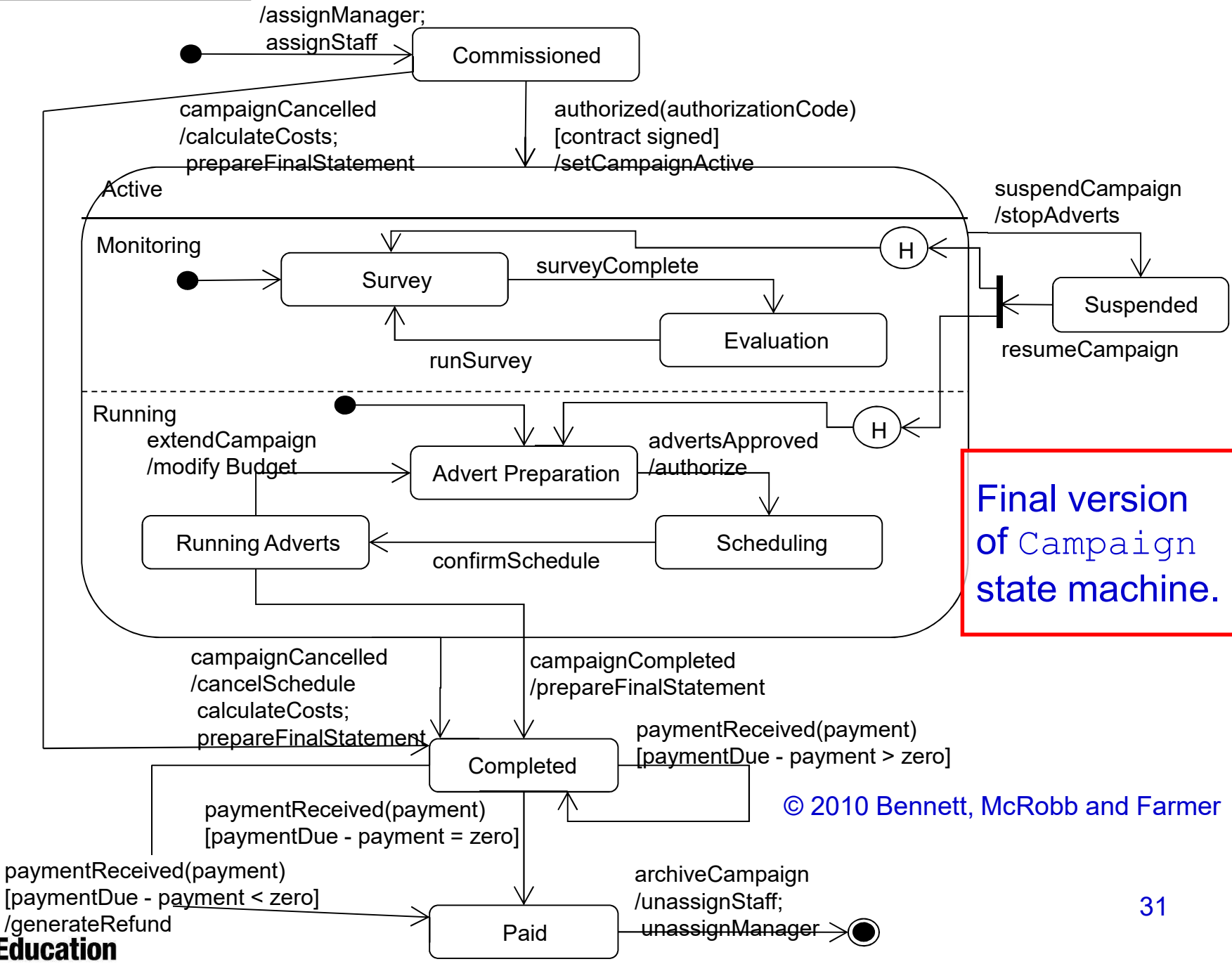


**Initial state machine for the Campaign class—a behavioral approach.**





Revised state machine for the Campaign class.



Final version of Campaign state machine.

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# Life Cycle Approach

- Consider the life cycles for objects of each class.
- Events and states are identified directly from use cases and from any other requirements documentation that happens to be available.
- First, the main system events are listed.
- Each event is then examined in order to determine which objects are likely to have a state dependent response to it.



# Life Cycle Approach Steps

1. Identify major system events.
2. Identify each class that is likely to have a state dependent response to these events.
3. For each of these classes produce a first-cut state machine by considering the typical life cycle of an instance of the class.
4. Examine the state machine and elaborate to encompass more detailed event behaviour.

# Life Cycle Approach Steps

5. Enhance the state machine to include alternative scenarios.
6. Review the state machine to ensure that is consistent with the use cases. In particular, check that the constraints that the state machine implies are appropriate.
7. Iterate through steps 4, 5 and 6 until the state machine captures the necessary level of detail.
8. Ensure consistency with class diagram and interaction diagrams and other state machines.

# Life Cycle Approach

- Less formal than the behavioural approach in its initial identification of events and relevant classes.
- Often helpful to use a combination of the two, since each provides checks on the other.

# Protocol State Machines

- UML 2.0 introduced a distinction between protocol and behavioural state machines.
- All the state machines so far have been behavioural.
- Protocol state machines differ in that they only show all the legal transitions with their pre- and post-conditions.

# Protocol State Machines

- The states of a protocol state machine cannot have
  - entry, exit or do activity sections
  - deep or shallow history states
- All transitions must be protocol transitions

# Protocol State Machines

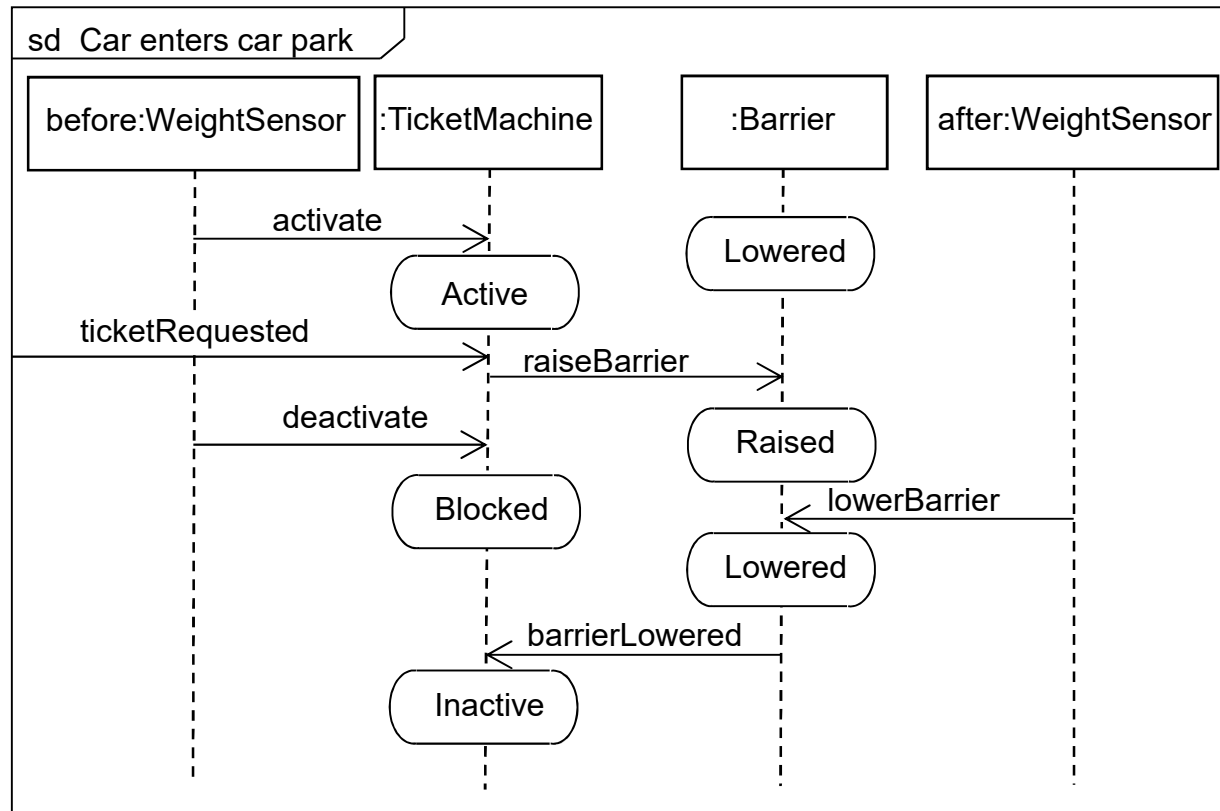
- The syntax for a protocol transition label is as follows.

```
' [' pre-condition ']' trigger '/'
```

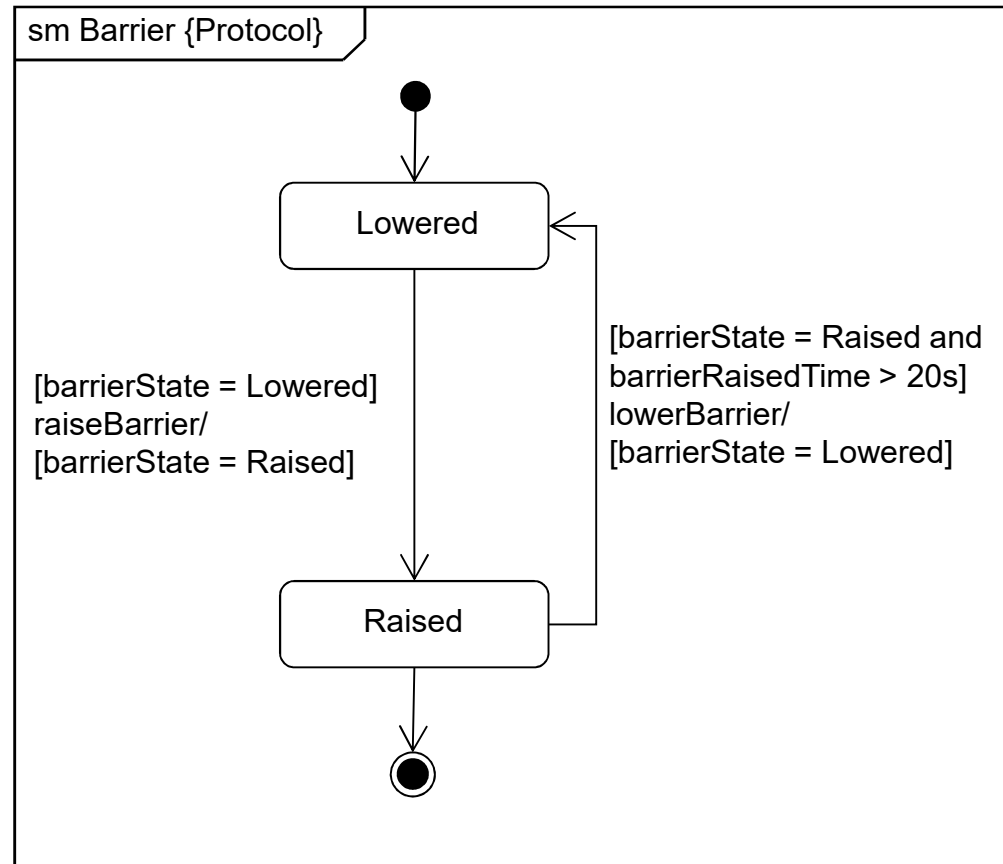
```
' [' post-condition ']'
```

- Unlike behavioural transitions protocol transitions do not have activity expressions.

# Sequence Diagram for Protocol State Machine Example



# Protocol State Machine





# Consistency Checking

- Every event should appear as an incoming message for the appropriate object on an interaction diagram(s).
- Every action should correspond to the execution of an operation on the appropriate class, and perhaps also to the dispatch of a message to another object.
- Every event should correspond to an operation on the appropriate class (but note that not all operations correspond to events).
- Every outgoing message sent from a state machine must correspond to an operation on another class.

# Consistency Checking

- Consistency checks are an important task in the preparation of a complete set of models.
- Highlights omissions and errors, and encourages the clarification of any ambiguity or incompleteness in the requirements.

# Summary

In this lecture you have learned about:

- how to identify requirements for control in an application;
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- how to develop state machine diagrams from interaction diagrams;
- how to model concurrent behaviour in an object;
- how to ensure consistency with other UML models.

# References

- UML 2.2 Superstructure Specification (OMG, 2009)
- Douglass (2004)  
(For full bibliographic details, see Bennett, McRobb and Farmer)